



Motion Controller TJ1-MC16

URL: <https://www.sxplc.com/motion-controller-tj1-mc16>

Product data sheet

Item		Details	
Model		TJ1-MC16	TJ1-MC04
Number of axes		16	4 (+1 using TJ1-FL02 unit)
Number of inverters and I/O modules		8 maximum (Inverters in speed or torque mode)	
Number of MECHATROLINK-II master units		Up to 4 MECHATROLINK-II master units (see below TJ1-ML16/ML04) can be connected	
Cycle time		Selectable 0.5 ms, 1 ms or 2 ms	
Programming language		BASIC-like Motion language	
Multi-tasking		Up to 14 tasks running simultaneously	
Built-in Digital I/O		16 Inputs and 8 Outputs, for general purpose	
Measurement units		User definable	
Available memory for user programs		500KB	
Data storage capacity		Up to 2 MB flash data storage	
Saving program data, motion controller		SRAM with battery backup and Flash-ROM	
Saving program data, personal computer		Trajexia Motion Perfect software manages a backup on the hard disk of the personal computer.	
Communication ports		1 Ethernet port and 2 serial ports	
Firmware update		Via Trajexia software tool	
Ethernet port	Electrical characteristics	Conform to IEEE 802.3 (100BaseT)	
	Connector	RJ45 Ethernet connector	
Serial port	Electrical characteristics	Conform 1 port to RS232C and 1 port to RS485/RS422A (selectable by switch)	
	Connector	SUB-D9 connector (Counterpart included in the package)	
	Synchronization	Start-stop synchronization (asynchronous)	
	Baud rate	1200 / 2400 / 4800 / 9600 / 19200 / 38400 bps	
	Transmission format	Databit Length	7 or 8 bit
		Stop Bit	1 or 2 bit
		Parity Bit	Even/Odd/None
	Transmission mode	Point-to-multipoint (1:N)	
	Transmission protocol	RS-232C (1:1)	Host Link master protocol, Host Link slave protocol, ASCII general-purpose
		RS-422A (1:N)	Host Link master protocol, Host Link slave protocol, ASCII general-purpose
		RS-485 (1:N)	ASCII general-purpose
	Galvanic isolation	RS422A port	
	Communication buffers	254 bytes	
	Flow control	None	
	Terminator	Yes, selectable by switch	
	Cable length	15 m for RS232 and 500 meter for RS422/485	

